

# Sampling from a Gaussian in high dimensions

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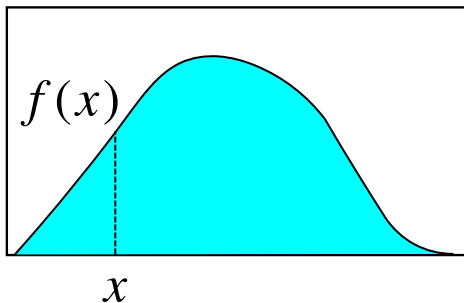
Data 2016



- want to test samplers in  $\geq 10^7 D$
- HMC seems champion but worry that leapfrog integrator too unstable in very high dimensions
- can we take over characteristics of HMC: use gradient, unit acceptance
- *silly example* SKILLING: unit Gaussian
- difficult in high D if matrices too large to be inverted/stored. Wiener filter example

$$\text{posterior mean} = D^{-1} R N^{-1} \mathbf{d}, \quad D = S^{-1} + R N^{-1} R$$

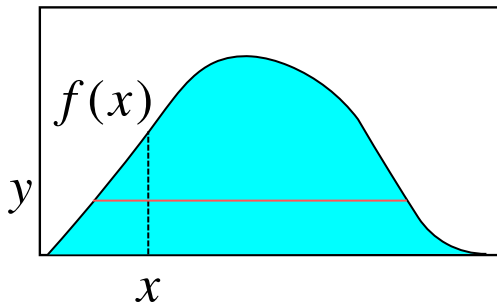
## Slice sampling: Sample under the curve $f(x)$



Auxiliary variable  $x \rightarrow (x, y)$   
sample  $P(x, y) = \text{const.}$  with Gibbs

- 1 vertical slice:  $y \sim \mathcal{U}_{[0, f(x)]}$
- 2 horizontal slice:  $x \sim \mathcal{U}_S, S = \{x \mid f(x) \geq y\}$

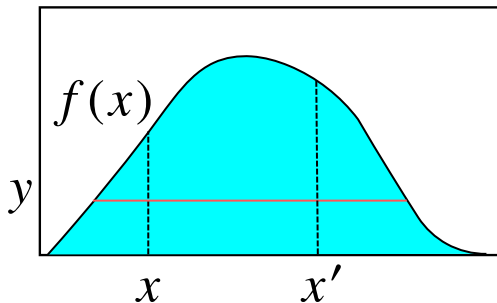
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# Slice sampling as a Metropolis algorithm

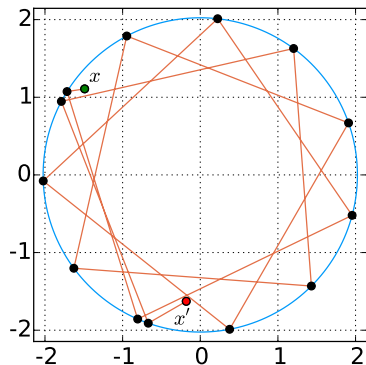
accept new  $x'$  if

$$u \leq \frac{f(x')}{f(x)}, \quad u \sim \mathcal{U}_{[0,1]}$$

if  $u$  known before  $x'$  proposed, we know all  $x' : f(x') \geq y \equiv u f(x)$   
 $\Rightarrow$  no point on slice is rejected

## special case of HMC

- flat potential
- new momentum at start of trajectory
- particle moves in straight line
- kinetic energy conserved in reflection
- integrate for time  $T$
- here: bounce point analytically known
- cost: 1 function + 1 gradient  $\forall$  bounce



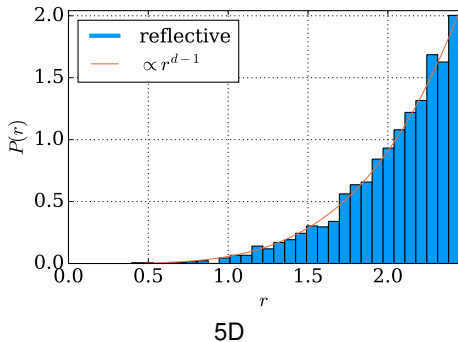
unit Gaussian in 2D: slice

$$\begin{aligned} S &= \{x \mid f(x) \geq y\} \\ &= \text{ball of radius } r_{\max} \end{aligned}$$

# Concentration of measure

uniform distribution on ball of radius  $r_{\max}$  in  $d$  dimensions, volume grows exponentially with  $d$  at boundary. On dimensional grounds

$$P(r) dr = \frac{d}{r_{\max}} \left( \frac{r}{r_{\max}} \right)^{d-1} dr$$

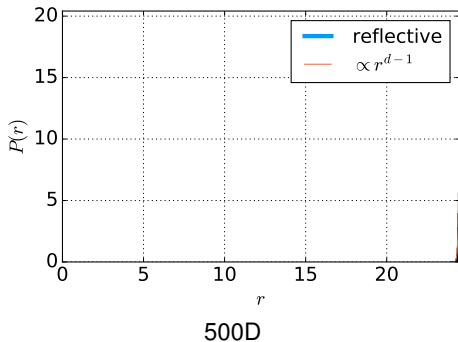




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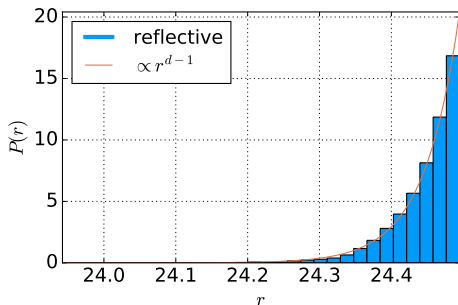


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all probability at surface, not inside



500D zoom

Estimate expectation value of  $g(x)$  with Monte Carlo

$$\bar{g} = \frac{1}{N} \sum_i g(x_i)$$

$$V[\bar{g}] = \frac{V[g]}{N} \times \tau$$

$$ESS = \frac{N}{\tau} \text{ or just } \frac{1}{\tau}$$

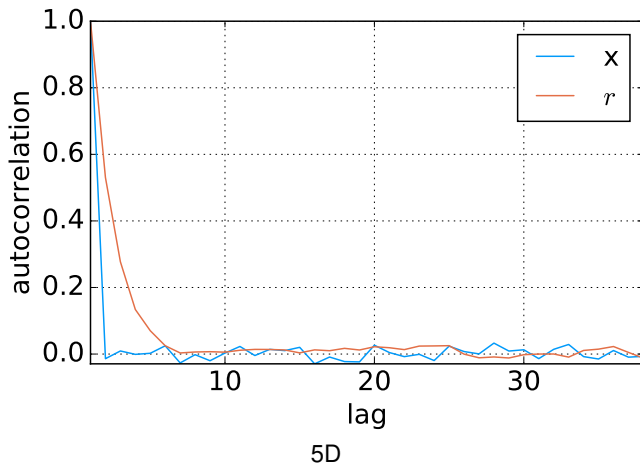
integrated autocorrelation time from autocorrelation  $\hat{C}$  at lag  $t$

$$\tau = 1 + 2 \sum_{t=1}^{\infty} \hat{C}(t)$$

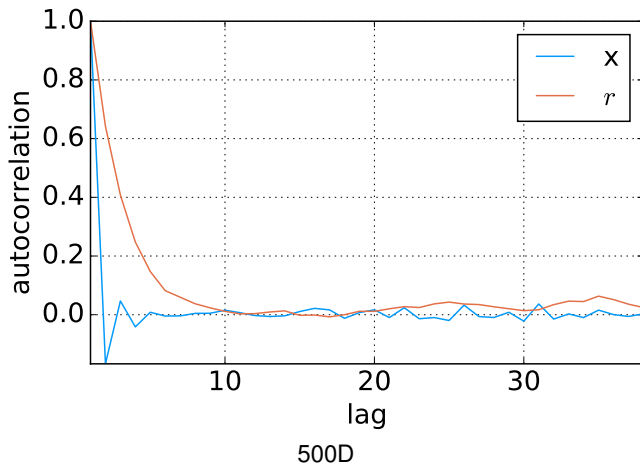
Independent samples  $\Rightarrow \tau = 1$

estimating  $\tau$  is nontrivial!

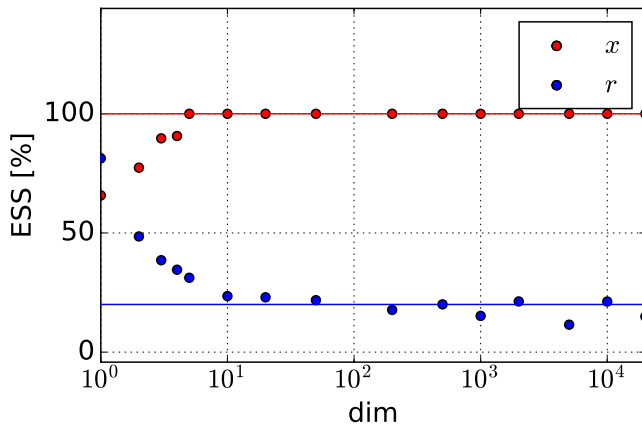
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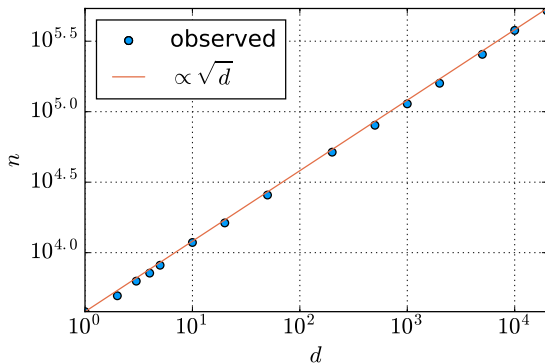


## Sampling performance for reflections



- fixed  $T$
- $x$ : small  $T$ , small ESS, capped at 100 %
- $r$ : limiting ESS with scatter, independent of  $T$

# Bounces: universal behavior



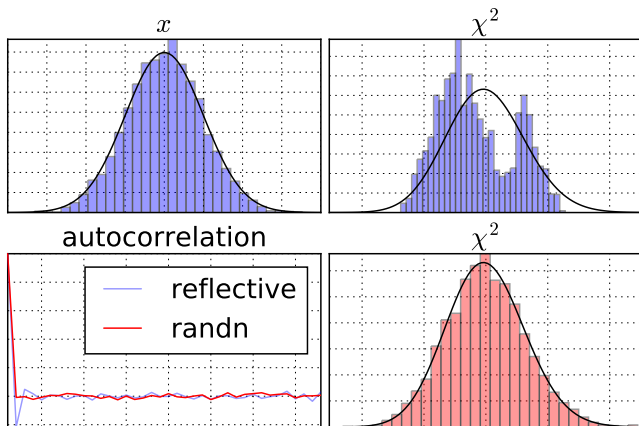
same runs as before, number of reflections (cost/iteration)

$$n \approx n(d_0) \sqrt{d/d_0}$$

simple geometric arguments?

compare to unconstrained HMC: cost  $\sim d^{1/4}$

# Back to slice sampling

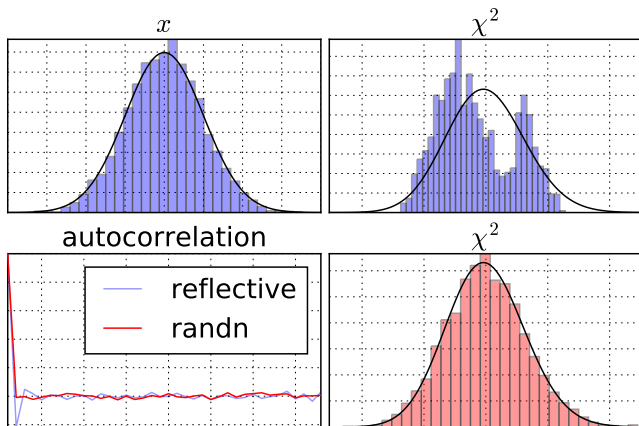


500 D

change  $r_{\max}$ , bounce for time  $T$ , update  $r_{\max}$ , repeat



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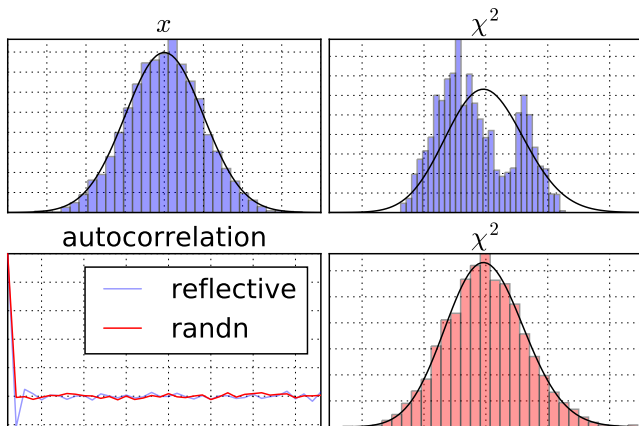


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Works very well in 1D subspace!

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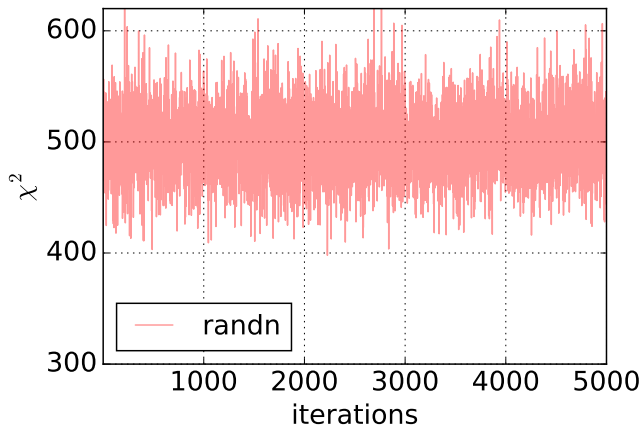
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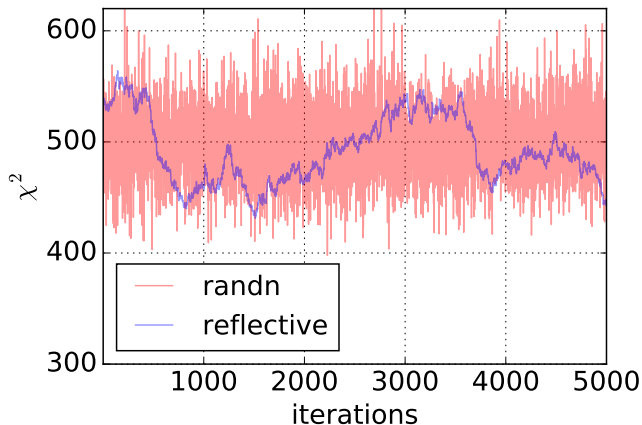
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$$u \leq \frac{f(x')}{f(x)} \Rightarrow \log f(x') \geq \log f(x) + \log u$$

$$u \sim \mathcal{U}_{[0,1]} \Rightarrow \log u \sim \text{Exp}(1) \in \mathcal{O}(1)$$

Change to  $\log f$  (energy) indep. of  $d$ !

$$f(x) = \prod_{i=1}^d \mathcal{N}(x_i | 0, 1) \Rightarrow \log f(x) \sim -\frac{1}{2}x^2 = -\frac{1}{2} \sum_{i=1}^d x_i^2 \in \mathcal{O}(d)$$

independent sampler

$$E[x^2] = d, \quad V[x^2] = 2d$$

so fluctuations are  $\mathcal{O}(\sqrt{d})$ . Random walk in 1D needs  $d$  steps of  $\mathcal{O}(1)$  to travel a distance  $\sqrt{d}$

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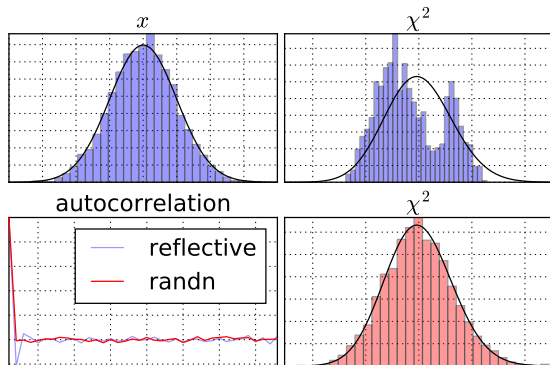
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# What can we do?



What if we add one or more auxiliary variables to increase fluctuations?

$$f(x) \rightarrow f(x)g(y)$$

$$\text{In HMC: } x \rightarrow (x, p)$$

## Scaling of densities

Can we get a scalar auxiliary variable  $y \sim g(y)$  to scale like  $d \mathcal{N}(0, 1)$  variables?  
I tried in vain. Seem prohibited by normalization

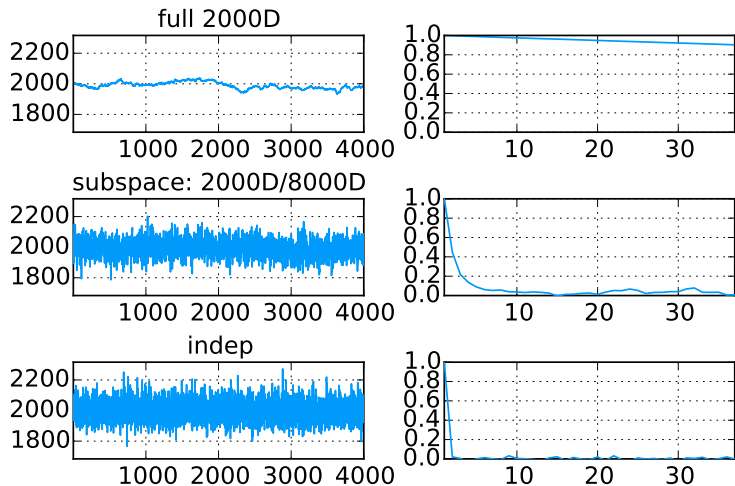
$$1 = \int dy g(y), g(y) \geq 0$$

volume  $\propto \exp(1)$

More rigorous derivation?



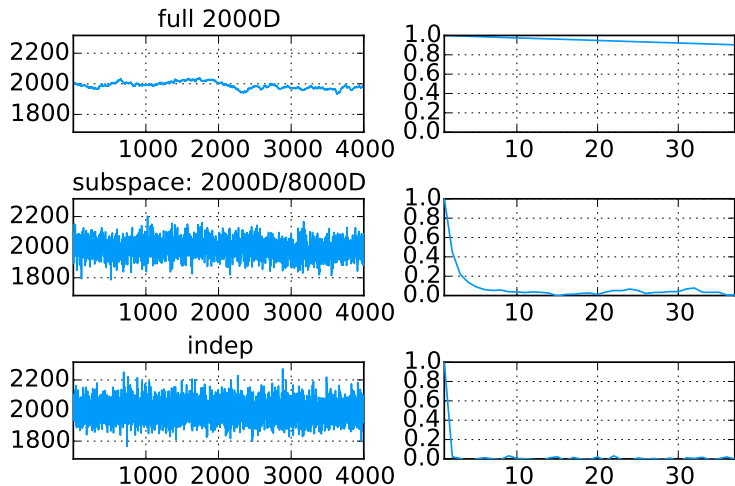
# Lots of auxiliary variables



$|\chi_n^2 - \chi_{n-1}^2|: 1 \rightarrow 43 \rightarrow 70$   
ESS: 0.2%  $\rightarrow$  26%  $\rightarrow$  100%  
#bounces: 72k  $\rightarrow$  142k

For 8x cost, at least 100x more indep. samples

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# Conclusion

- standard Metropolis fails in high dimensions
- auxiliary variables can boost ESS/cost reflective slice sampling dramatically